





Analysis Report

Multiple Fin Assembly Analysis Report

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Terminology

I. Introduction

II. Openrocket Analysis

A. Additional Fin Analysis Added to the Rear Fuselage

B. Analysis of Additional Fins Added to the Front Body Without Engine

C. Analysis of Additional Fins Added to the Front Body With Engine

D. Determined for the Next Stage

III. Solidworks Designs

- Reference Rocket Solidworks Design

- Multistage Rocket 1-C Solidworks Design

- Multistage Rocket 1-C Solidworks (Rotated 45 Degrees) Design

- Reference Rocket (With Inverted Fins) Solidworks Design

IV. Ansys Analysis

a. Reference Rocket Ansys Analysis

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- c. Multistage Rocket 1-C (Rotated 45 Degrees) Ansys Analysis
- d. Reference Rocket (With Inverted Fins) Ansys Analysis

V. Results and Interpretation of Analysis

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- Pressure and Velocity Contours





1) Introduction

This report; going beyond the classical rocket designs, which have now become a standard in the rocketry industry, preferred due to its practicality and various advantages, designed as four equal-sized fins attached to the lower body; the effect of a larger number of additional winglets positioned in different places than the standard fins on the general flow and flight was examined, and the analyzes obtained through Openrocket and Ansys applications were shared on the basis of these examinations.

2) Openrocket Analysis

First stage, the preliminary analysis of the possible rocket designs to be compared were tested through the Openrocket program, and if successful results are obtained from the tests, which of the designs that give successful analysis results after the reasons are stated, which of the designs that give the successful analysis result are desired to be taken to the next stages, proceed to the next stages with the selected designs and proceed to the reporting processes has been continued.

In the preliminary analyzes made over the Openrocket program, rocket designs were examined by dividing them into 3 basic classes:

- A. Additional Fin Analysis Added to the Rear Fuselage
- B. Analysis of Additional Fins Added to the Front Body Without Engine
- C. Analysis of Additional Fins Added to the Front Body With Engine

The basic conditions that the designs must meet in order to pass the Openrocket tests are listed as follows:

-1 kg payload should be able to be increased up to 1500-2000 meters altitude.

-The average wind speed should be 2 m/s.

-The launch pad must be 3 meters and the launch angle must be 5 degrees.

-The minimum ramp speed should be 20 m/s.

-The stability value during flight should not exceed 1.5-3 cal range.

-The properties of the materials to be used are also specified as follows:

Payload height 350 mm, diameter 143 mm.

Main Parachute height 100 mm, diameter 146 mm, weight 500 g.

Drogue Parachute height 50 mm, weight 100 g.

Avionics Box height 150 mm, diameter 75 mm, weight 600 g.

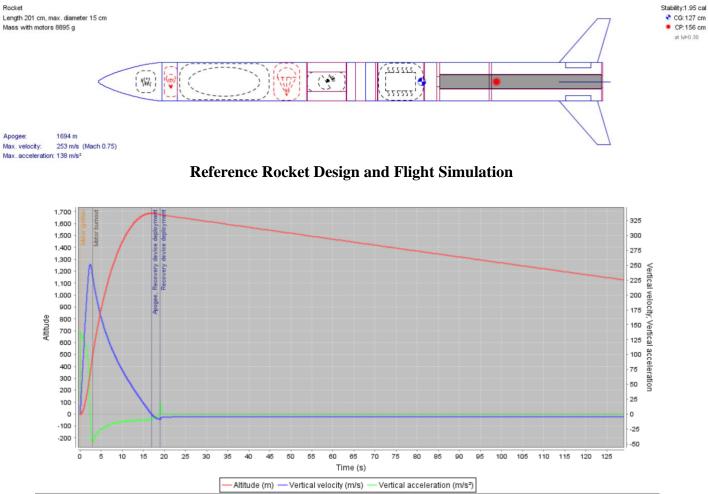




A. Analysis of Additional Fins Added to the Rear Body In the

In the rocket designs used in this article, 4 fins have been added in addition to the standard rocket structure and the shapes of all the fins used are designed to provide the necessary conditions, especially the necessary stability during the flight.

Our additional wingless rocket design and flight simulations, which we refer to in the comparisons, are as follows:

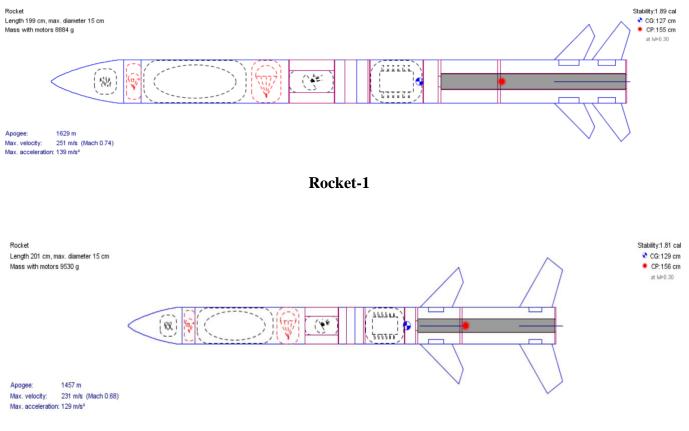


In the first design trials, in addition to the current number of 4 fins, which is considered standard, it was mounted to the lower fuselage and subjected to various tests by adding 2 and 3 additional fins in different positions in separate trials, but as a result of these tests, it was observed that the rocket could not provide a stable flight during flight. In the new design trials that were continued afterwards, it was observed that a smooth and stable flight was at the highest efficiency with 4 additional fins to be added. As the main reason for this situation, we have argued that the arrangement of the fins in different numbers has different geometries, and therefore the fins in the front will direct air currents in a way that is not suitable for the fins at the rear, causing an uneven distribution of forces.





The trial tests of the next item A were made to see whether adding the fins to the rear part of the rocket body, or the front part, would yield more efficient results. 4 different test rocket designs were created. In the first and second rockets, the fins were designed to have surface areas close to each other and close to the rear part of the first rocket and close to the front of the fuselage in the second rocket.



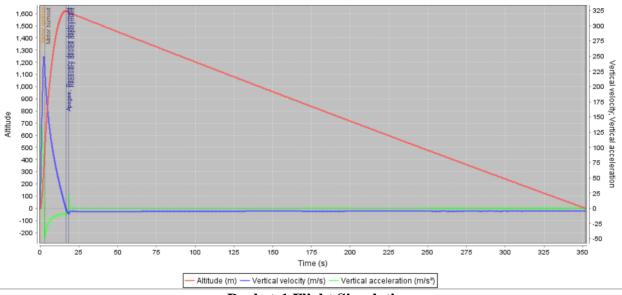


Although the stability of the first two test rockets gave an uneventful result between 1.5 and 3 cal during their flight, it was observed that the stability and the maximum height expected to be reached decreased significantly as the fins were moved from the rear to the front. Fins forward

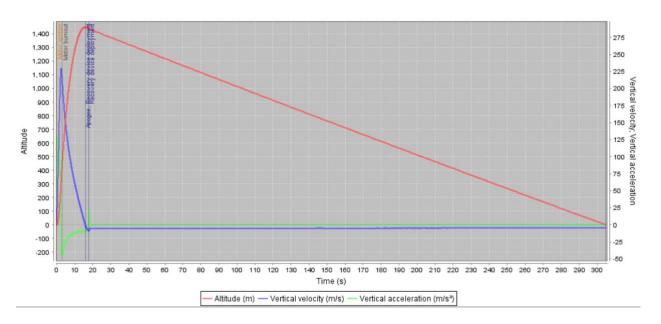
As carrying reduces stability, the fins need to be further enlarged in order to compensate for this. Since the growing fins are also made of aluminum, the net weight of the rocket has increased by about 700 g after the changes. As a result of this increase in mass for the sake of stability, the maximum height has decreased by approximately 170 m and similar decreases have been experienced in the estimated maximum speed and acceleration to be reached.







Rocket-1 Flight Simulation

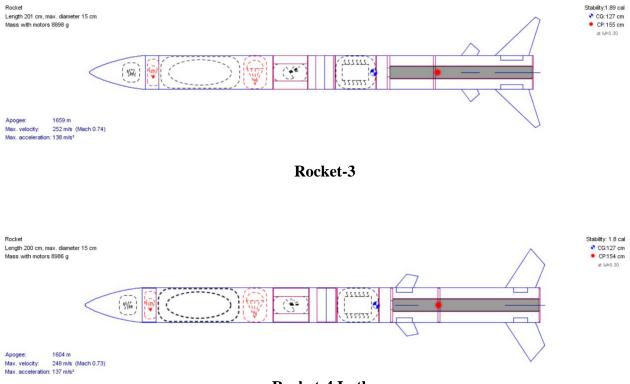


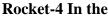
Rocket-2 Flight Simulation





Following the results obtained in rockets with close surface areas, the 3rd and 4th rockets, whose surface areas are far apart, that is, carrying 4 large and 4 small fins, were also subjected to similar tests and simulations.





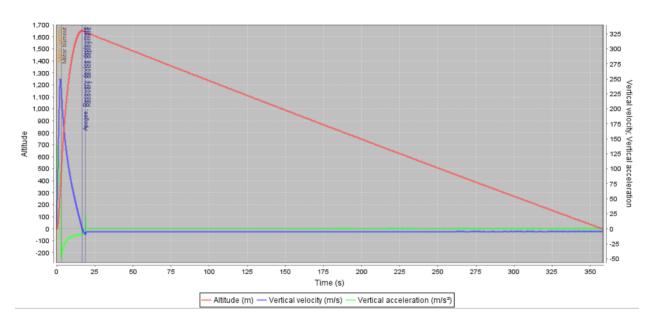
In the simulations, the 3rd and 4th rockets, which were designed with winglets with four large and four small surface areas, were able to reach higher altitudes than the 1st and 2nd rockets with similar large surface areas. Again, as we noticed when comparing the first two rockets, there was a decrease in stability in these simulations as a result of the fins moving away from the rear, but since the fins were smaller and naturally lighter than the previous one, it was not necessary to enlarge the second winglet much. The price of the stability provided by the change of the second aileron areas with small differences in this way was a loss of altitude of only 55 meters. There were also smaller decreases in maximum velocity and acceleration compared to the first two rockets.

To evaluate the results in general; In line with simulations, it is possible to add fins to the rear fuselage without adding an engine and to fly under these conditions. In order not to disturb the flight stability of the number of fins and their geometry, 4 or more fins can be used provided that they are mounted at equal angles. However, the use of more than 4 fins is not recommended as it will be a serious additional weight for the rocket, and it should be examined whether there is a problem in the flow with deeper analysis. It is important that the size of the fins to be added is smaller than the original fins and that these added fins are positioned as close as possible to the main fins and correctly at the rear of the rocket, for the sake of stability, both altitude and speed of the rocket are lost at a minimum level. The most important result observed in all these trials is

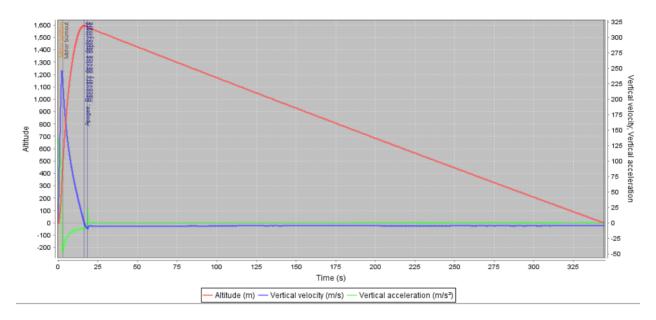




that the addition of a different fin to the lower body of the rocket, under any circumstances, could not provide as efficient flight as the normal rocket design without any additional fins. In other words, designing a rocket by attaching an additional wing to the rear fuselage in addition to the standard rocket design is a superfluous task unless there is a special reason, it is inefficient. It is possible to see this result visually in the flight simulations given below.



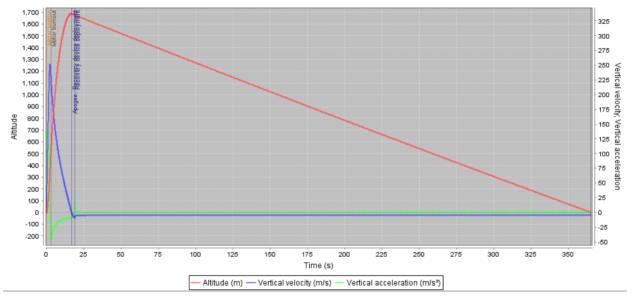
Rocket-3 Flight Simulation



Rocket-4 Flight Simulation







Flight Simulation of Basic Rocket with No Additional Fins (Reference Rocket)

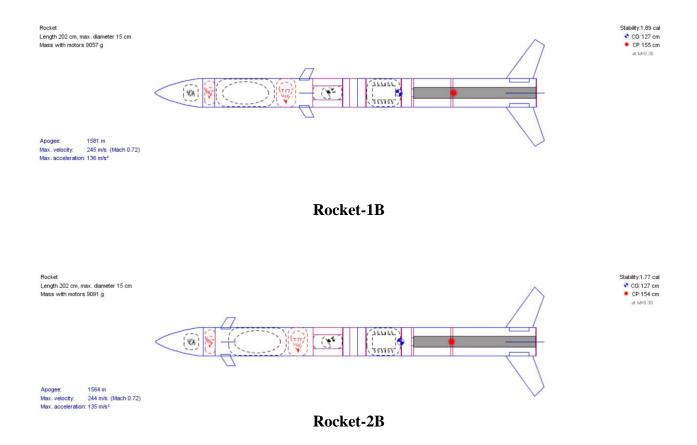




B. Analysis of Additional Fins Added to the Front Body Without Engine

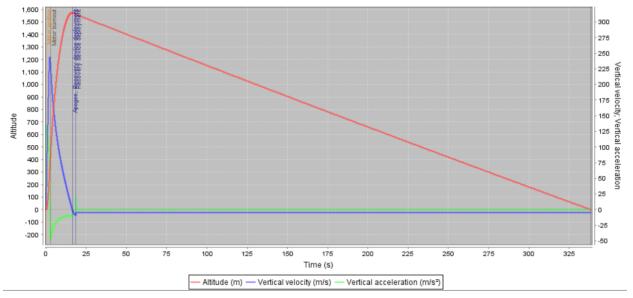
In this item, as in item A, simulations were continued by using 4 additional fins. As the name suggests, in this article, fins were added to the upper rocket body without using an additional engine. In other words, it can be thought of as 4 fins that are additionally mounted on the upper body of a standard rocket.

As noticed in the experiments; The fins added to the upper body of the rocket significantly reduce the stability by changing the center of gravity and pressure center. If this front-mounted wing is too large, stability values may even drop below 1, and to compensate for this, we need to design the rear fin in huge dimensions. Of course, this choice should be avoided, as the growing fin will have more weight. For these reasons, only small fins and draft tests were made on the front fuselage in the simulation trials and the results were analyzed according to these. Two test rockets and flight simulations with these rockets are as follows:

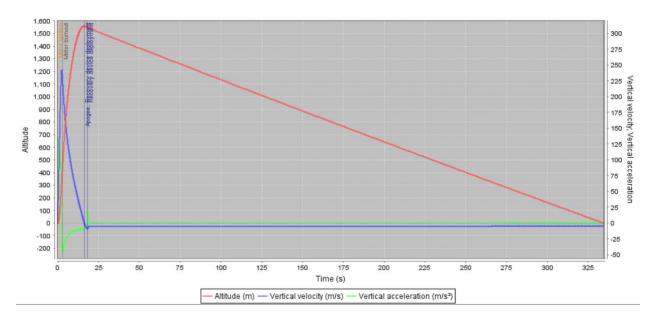








Rocket-1B Flight Simulation



Rocket-2B Flight Simulation As

As can be seen, there is no significant difference in the result between the two paintings and the two rockets. Compared to the differences between the rockets in item A, the altitude difference of the rockets in item B is a very small value, such as 17 meters. In item A, this loss was simulated as the lowest 55 meters. The rockets with additional fins designed in this article also seem to be designed successfully in real life, as seen from the simulations. However, the results show that the rocket designs in item B are more inefficient than the characteristics of a rocket with no additional fins, as in item A. You will not need to use such an additional fin unless you have a goal of tampering with the rocket's center of pressure.





According to the general experience obtained as a result of the tests, if you are sure to install additional fins, you should attach these additional fins to the front body to reduce stability and to the rear body to increase it. Considering these conditions, special designs can be made that have sufficient qualifications and can successfully perform the flight, although they do not have absolute efficiency.

The design of the SpaceX Starship rocket, which was successfully launched at the end of 2020, was exactly the type of rocket mentioned in article B. The main differences from item B are that this rocket has a very large nose cone, the mentioned additional fins are placed 2 on top of this nose cone, and there are only 2 fins in the lower body, that is, in the basic position. There is a critical reason for making this interesting design, which is very difficult to manufacture: soaring. We see that the rocket flies calmly towards a certain height during its flight, then when the target point is reached, the rocket engines are turned off, the Starship rocket moves to a horizontal position and starts to glide. to the landing area

This floating rocket is designed to make a vertical landing again. The rocket engines are reignited, the rocket is brought to a vertical position with the propellant forces and begins to make a vertical descent. However, due to the failure of one of the engines, the landing is attempted only with the remaining rocket engines and the Starship rocket, which cannot slow down naturally enough, crashes to the ground and explodes.



SpaceX Starship Rocket And Gliding Moment





C. Analysis of Additional Fins Added to the Front Body Without Engine

The most critical item, item C, is based on a multi-engine system. In other words, while the main rocket engine is working up to a certain altitude, after the main engine is exhausted, the separation between the bodies occurs and the second rocket engine is activated and our rocket continues its flight. Apart from the difficulty of the design, the high synchronization requirement and the low success rate compared to the classic, we can also analyze this structure in terms of aerodynamics. The experiment we did

We also succeeded in obtaining successful results in the simulations of their designs.

Since adding fins in A and B items did not give us the desired result in terms of altitude, we explained that it was unnecessary unless there were special conditions and requests. However, there is no altitude loss when an extra engine is involved. Although the weight of the extra rocket and additional fins reduces the maximum speed and maximum acceleration, our altitude values are

these designs are above normal values.

The fins to be added to the rocket must be as far from the nose cone as possible and as close to the engines as possible. If the additional fins are close to the nose cone, it will affect the flight of the rocket in two stages:

The first stage is the stage in which the rocket flies as a whole, at which the position of the fin will decrease the stability values of the rocket and to balance it,

the fins will need to be designed even larger. This will reflect to us as extra weight and altitude loss.

The second stage is the post-departure flight process. After the rocket has successfully disengaged, only the upper body and nose cone will remain. So the upper body will actually act like any other rocket. If we position the fins close to the nose cone, the center of gravity and the center of pressure will change position significantly and the stability of the rocket after separation may even decrease to values below zero. This means that the rocket starts somersaults and crashes into the ground unsuccessfully. For these reasons, additional fins should be as small as possible and adequately sized for post separation stability, and should be positioned as close as possible to the rocket engine and as far away from the nose cone as possible. When these conditions are met, a successful flight and landing is of course possible.

Rocket Length 154 cm, max. diameter 15 cm Mass with motors 7888 g Stability: 1.93 cal CG:95.8 cm CP: 125 cm

 Apogee:
 2366 m

 Max. velocity:
 230 m/s (Mach 0.69)

 Max. acceleration:
 74.9 m/s²

Rocket-1C Stage-1



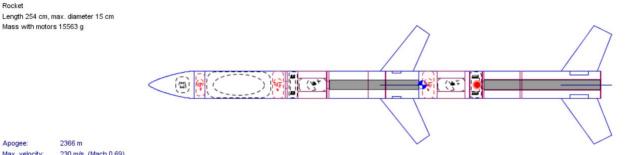
Rocket



Stability: 2 cal

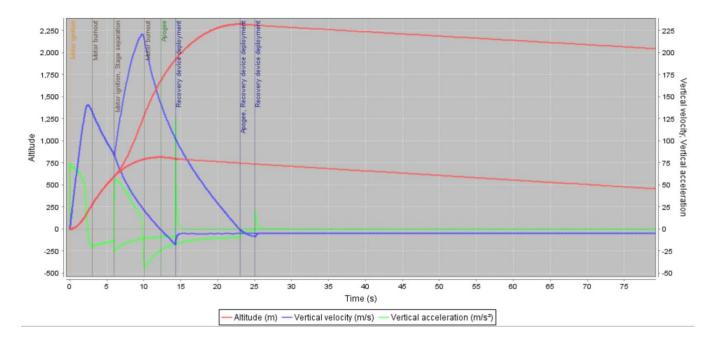
CG:150 cm

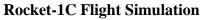
• CP:180 cm at N=0.30



Apogee: Max. velocity: 230 m/s (Mach 0.69) Max. acceleration: 74.9 m/s2

Rocket-1C Stage-2





As can be seen, the main task of a rocket to be designed in accordance with the C clause should be focused on high altitude. As a matter of fact, the system in space shuttles is also based on this logic. Extra rocket engine, extra fuel spent, extra parts, in short, a bigger rocket; means more expense.





D. Determined for the Next Stage

As a result of all our Openrocket analyzes, the rockets that are planned to be transferred to the Solidworks drawing stage in order to carry out detailed analyzes on Ansys and their types, along with their reasons, are as follows:

-Reference Rocket has been selected. In order to make a comparison, it was deemed appropriate to examine the flow of our reference rocket. In addition, the flow analysis of the reversed fins of the reference rocket was also carried out.

- Rocket-1C Stage-2 version has been selected. In order to compare the flow on it and to find the optimum blade mounting position; It has been deemed appropriate to make the designs with the position where the main fins and the additional fins will be parallel to each other and the position with an angle of 45 degrees between them, to be made over the Solidworks program and then to be subjected to Ansys analysis.

Other analyzed rocket designs were not selected for various reasons mentioned in their articles.





3) Solidworks Designs

Our Solidworks designs have been designed in accordance with the outlines of Openrocket designs and transferred to Ansys geometry with the "Parasolid" format so that we can use them in our Ansys analysis.

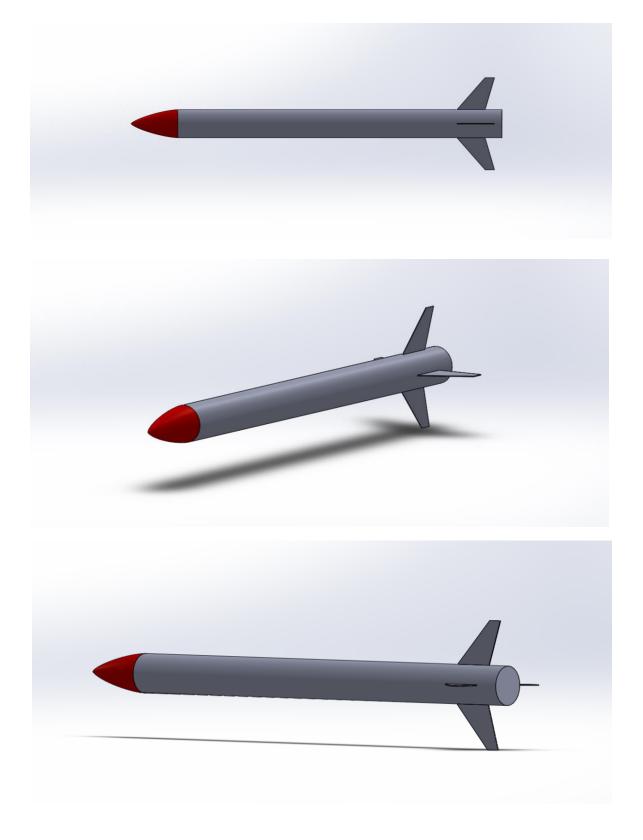
A minor careless issue was encountered while importing designs into Ansys:

During the assembly of the fins in Solid, the fins were not fully seated on the fuselage and millimetric errors occurred in the assembly of the straight cut fins to the curved fuselage. Solidworks drawings were reviewed in detail and necessary adjustments were made to the drawings. In this way, we did not have any problems while transferring our Solidworks designs to Ansys. Our Solidworks designs are shared as images below:

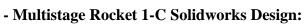




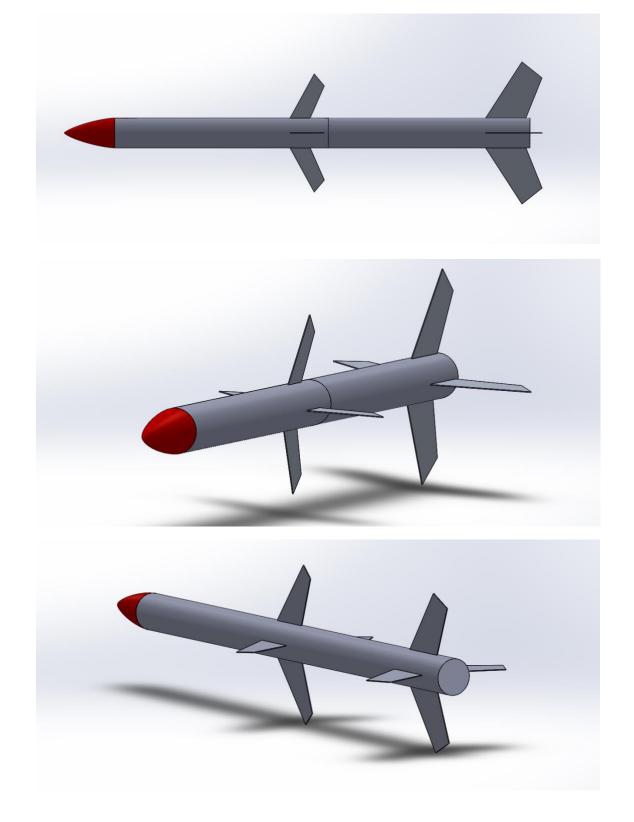
- Reference Rocket Solidworks Design:







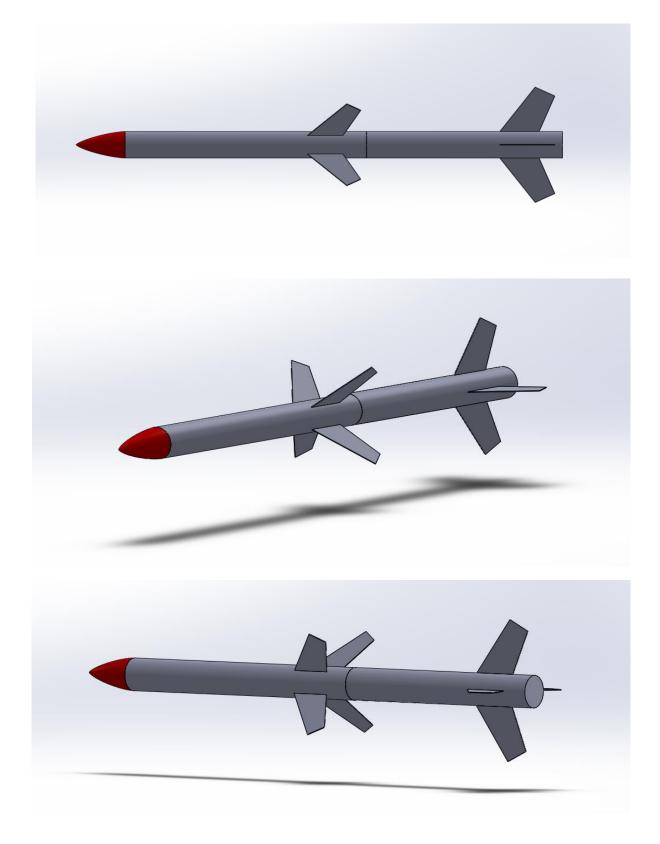








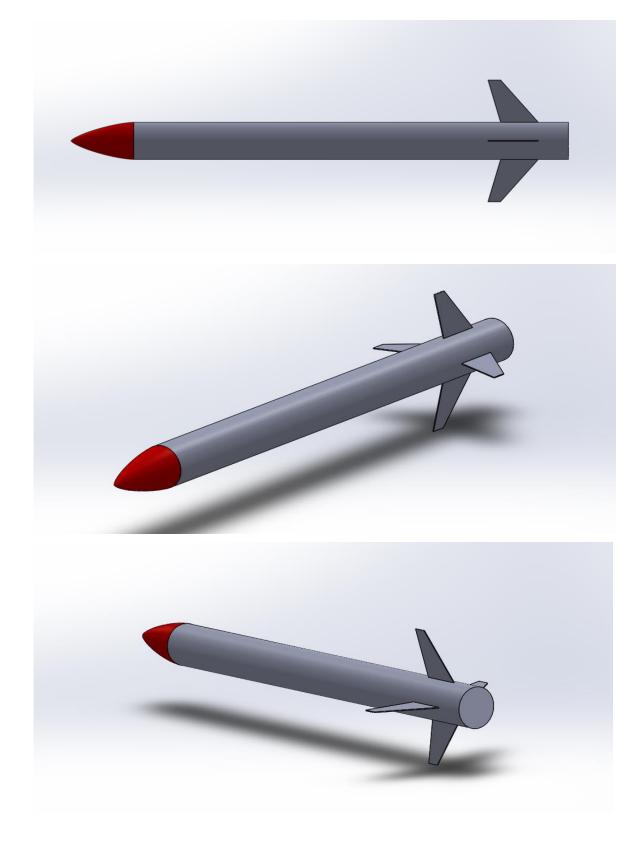
- Multistage Rocket 1-C (Rotated 45 Degrees) Solidworks Design:







- Reference Rocket (With Inverted Fins) Solidworks Design:







4) ANSYS Analysis

In our ANSYS analyzes, our flow analyzes were performed over Fluid Flow (Fluent). Necessary data and information were determined via Openrocket and air was used as the fluid. Geometry is drawn with a single control volume, designated as the Parasolid (.x_t) extension of Solidworks designs. However, when drawn with a single control volume, the meshing process was quite problematic. The computer, which rebuilt the entire rocket for a sizing given to the fins, started to make poor quality and long-lasting meshes. Therefore, the single control volume has been increased to two control volumes and the second control volume has been plotted to coincide exactly with the fins. In this way, when sizing is given, the processes are accelerated and a mesh suitable for the solution is obtained by giving a small amount of sizing.

Although the mesh quality was tried to be ensured by deleting zero from the First Layer Thickness value before changing the control volume, it was abandoned because this would affect the solution and could not solve the mesh problem fundamentally.

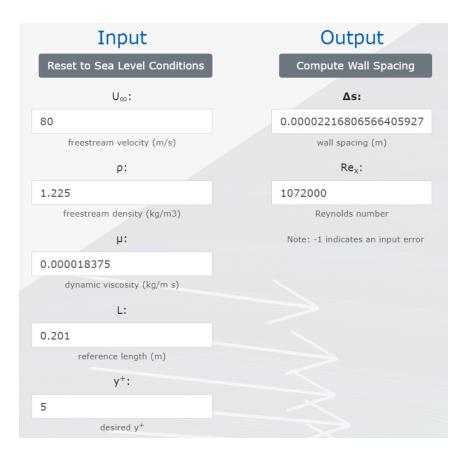
In addition to these, the rockets were transferred to the Ansys environment in a reduced ratio of 1/10 of the original, and in this way, the mesh and solution process was accelerated. In shrinking rockets, the flow velocity also changed in the ratio of the square root of the length ratio, and appropriate solutions were assigned to these shrunken rockets with their own reduced velocity values in Ansys calculations. Our First Layer Thickness values together with our Openrocket data, via the Y+ Calculator over the internet calculated.

The visuals and explanations regarding the analyzes of the rockets are given below in detail, separately:



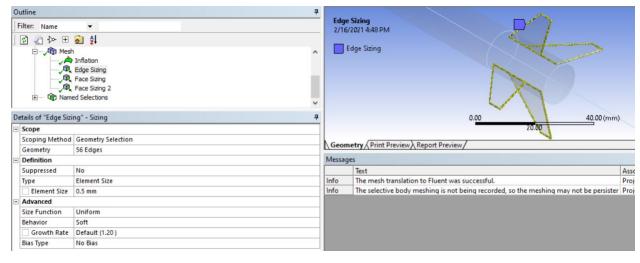


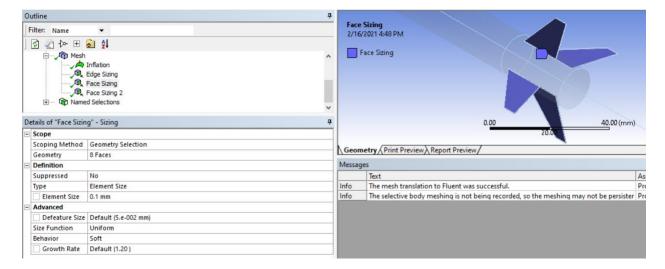
a) Reference Rocket Ansys Analysis



- Mesh

De	Details of "Inflation" - Inflation		
Ξ	Scope		
	Scoping Method	Geometry Selection	
	Geometry	2 Bodies	
	Definition	·	
	Suppressed	No	
	Boundary Scoping Method	Named Selections	
	Boundary	wall	
	Inflation Option	First Layer Thickness	
	First Layer Height	2.216e-002 mm	
	Maximum Layers	10	
	Growth Rate	1.2	
	Inflation Algorithm	Pre	





Outline		4			
Filter: Name	*		e Sizing 2 5/2021 4:49 PM		
🛃 🕢 🗁 🖽	6				
	n Inflation Edge Sizing Face Sizing Face Sizing 2 ed Selections		Face Sizing 2		
Details of "Face Sizi	ng 2" - Sizing	4			0.000 (mm)
Scope				5.000	
Scoping Method	Geometry Selection	Geor	metry (Print Preview) Rep	nort Preview /	
Geometry	12 Faces	Глеон	neuy/rint rieview/kep		
- Definition		Messa	ges		
Suppressed	No		Text		Assoc
Туре	Element Size	Info	The mesh translation to	Fluent was successful.	Projec
Element Size	5.e-002 mm	Info	The selective body mesh	hing is not being recorded, so the meshing may not be p	ersister Projec
- Advanced					
Defeature Size	Default (2.5e-002 mm)				
Size Function	Uniform				
Behavior	Soft				
Growth Rate	Default (1.20)				









What we have obtained after all your reviews and which are the basic evaluation criteria for us; Aspect Ratio, Skewness and OQ our values are as follows:

Quality	Jality		
Check Mesh Quality	Yes, Errors		
Target Skewness	0.6		
Smoothing	Medium		
Mesh Metric	Aspect Ratio 💌		
Min	1.1731		
Max	417.37		
Average	3.4837		
Standard Deviation	7.7117		

Mesh Metric	Skewness 💌
Min	2.4539e-004
Max	0.92175
Average	0.26455
Standard Deviation	0.14777

Mesh Metric	Orthogonal Quality
Min	2.7778e-002
Max	0.99934
Average	0.73465
Standard Deviation	0.14828

The number of the elements are as follows:

Statistics	
Nodes	1455083
Elements	3788746





Models			
Models	🖳 Viscous Model		\times
Multiphase - Off Energy - Off Viscous - SST k-omega Radiation - Off Heat Exchanger - Off Species - Off Discrete Phase - Off Solidification & Melting - Off Acoustics - Off Eulerian Wall Film - Off Electric Potential - Off Electric Potential - Off	Model Inviscid Laminar Spalart-Allmaras (1 eqn) k-epsilon (2 eqn) Transition k-kl-omega (3 eqn) Transition SST (4 eqn) Reynolds Stress (7 eqn) Scale-Adaptive Simulation (SAS) Detached Eddy Simulation (DES) Large Eddy Simulation (LES) k-omega Model Standard BSL SST	Model Constants Alpha*_inf 1 Alpha_inf 0.52 Beta*_inf 0.09 a1 0.31 Beta_i (Inner) 0.075 Beta_i (Outer) 0.0828 TKE (Inner) Prandtl # 1.176 TKE (Outer) Prandtl #	
Help	k-omega Options Low-Re Corrections Options Curvature Correction Production Kato-Launder Production Limiter Intermittency Transition Model	1 SDR (Inner) Prandtl # 2 SDR (Outer) Prandtl # User-Defined Functions Turbulent Viscosity none	•

Reference Values		
Compute from		
inlet		
	Reference Values	
	Area (m2)	0.04
	Density (kg/m3)	1.225
	Enthalpy (j/kg)	0
	Length (m)	0.201
	Pressure (pascal)	0
	Temperature (k)	288.16
	Velocity (m/s)	80
	Viscosity (kg/m-s)	1.7894e-05
	Ratio of Specific Heats	1.4
Reference Zone		

	173		5
Boundary Conditi	ions		<u> </u>
Zone Filter Text			÷
inlet			•
interior-part-solid outlet			Щ.
symmetry			⊕ .
wall			,
inlet			
Momentu		DPM Multiphas	· · · · · · · · · · · · · · · · · · ·
	elocity Specification Method Components	DPM Multiphas	•
Ve		DPM Multiphas	· · · · · · · · · · · · · · · · · · ·
Ve	elocity Specification Method Components Reference Frame Absolute	constant	• •
Ve	elocity Specification Method Components Reference Frame Absolute Initial Gauge Pressure (pascal) 0	constant	* *
Ve	elocity Specification Method Components Reference Frame Absolute Initial Gauge Pressure (pascal) 0 Coordinate System Cartesian (X, Y, Z) X-Velocity (m/s) 80 Y-Velocity (m/s) 0	constant	• • •
Ve	elocity Specification Method Components Reference Frame Absolute Initial Gauge Pressure (pascal) 0 Coordinate System Cartesian (X, Y, Z) X-Velocity (m/s) 80 Y-Velocity (m/s) 0 Z-Velocity (m/s) 0	constant	• • •
Ve	elocity Specification Method Components Reference Frame Absolute Initial Gauge Pressure (pascal) 0 Coordinate System Cartesian (X, Y, Z) X-Velocity (m/s) 80 Y-Velocity (m/s) 0 Z-Velocity (m/s) 0 Turbulence	constant constant constant constant constant	• • • • •
Ve Supersonic/1	elocity Specification Method Components Reference Frame Absolute Initial Gauge Pressure (pascal) 0 Coordinate System Cartesian (X, Y, Z) X-Velocity (m/s) 80 Y-Velocity (m/s) 0 Z-Velocity (m/s) 0	constant constant constant constant sity Ratio	• • • •

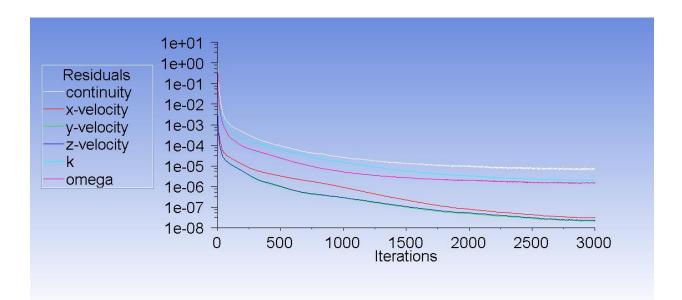
Solution Methods

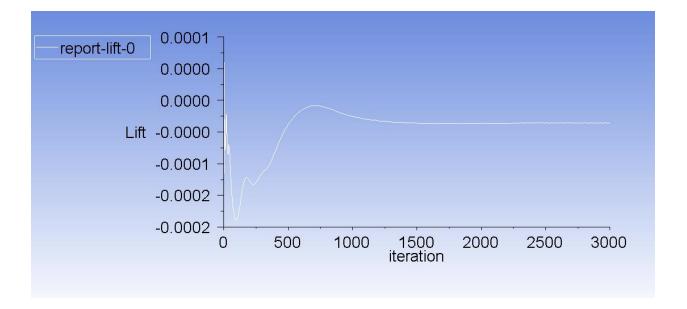
Scheme			
Coupled			-
Spatial Discretization			
Gradient			~
Least Squares Cell Based		•	
Pressure			
Second Order		•	
Momentum			r
Second Order Upwind		-	
Turbulent Kinetic Energy			
Second Order Upwind		•	
Specific Dissipation Rate			
Second Order Upwind		Ŧ	V
Transient Formulation			
	v.		
Non-Iterative Time Advancer	nent		
Frozen Flux Formulation			
Pseudo Transient			
Warped-Face Gradient Correc	tion		
High Order Term Relaxation	Options		





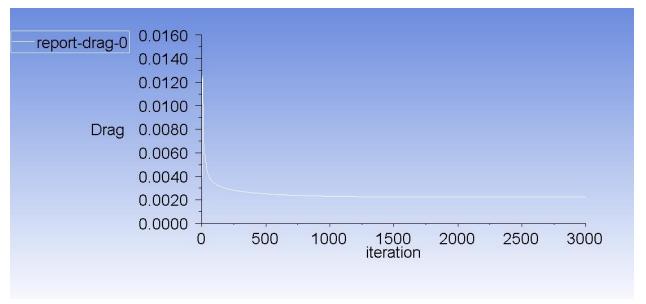
And finally hybrid initialization has switched to the stage of making a solution. Our solution graphics have been reached by giving approximately 4100 iterations. Drag and lift values were plotted simultaneously.



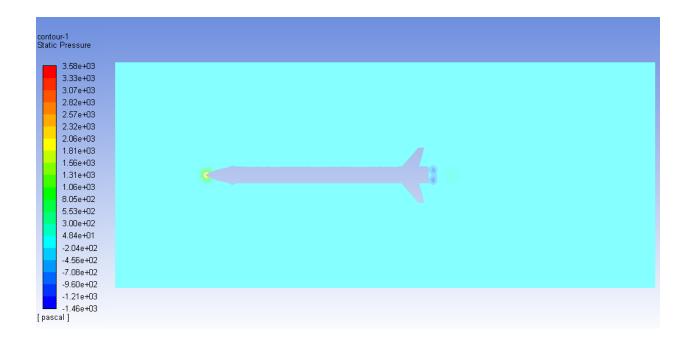






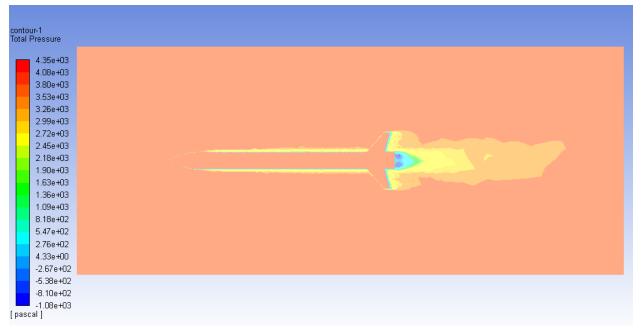


Pressure contours:

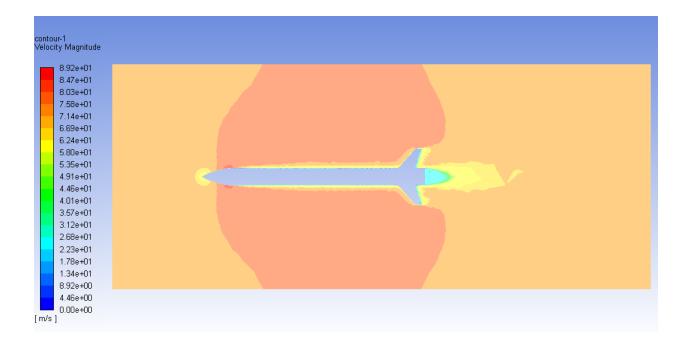






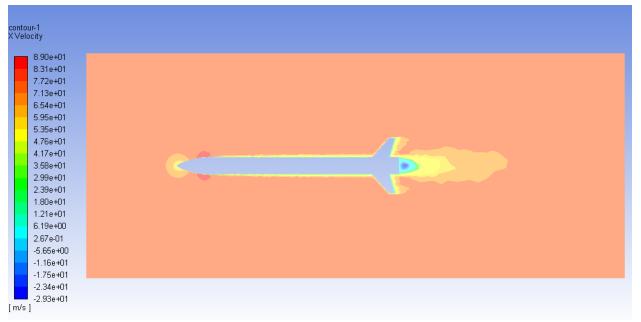


Velocity contours:







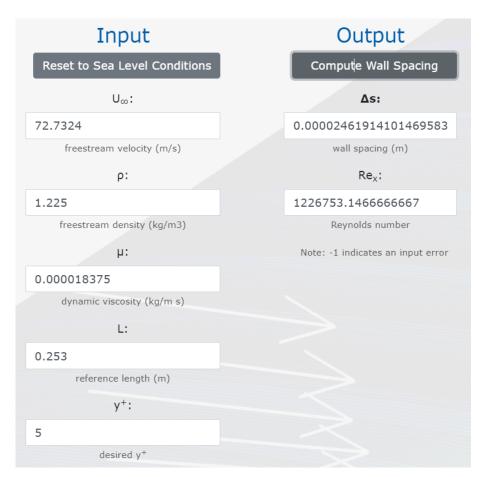


And thus, the analysis of our reference rocket was finished, and the analysis of the rockets we wanted to see started.





b) Multistage Rocket 1-C Ansys Analysis



-Mesh

De	Details of "Inflation" - Inflation			
Ξ	Scope			
	Scoping Method	Geometry Selection		
Geometry 2 Bodies		2 Bodies		
Ξ	Definition			
	Suppressed	No		
	Boundary Scoping Method	Named Selections		
	Boundary	wall		
	Inflation Option	First Layer Thickness		
	First Layer Height	2.4626e-002 mm		
	Maximum Layers	10		
	Growth Rate	1.2		
	Inflation Algorithm	Pre		

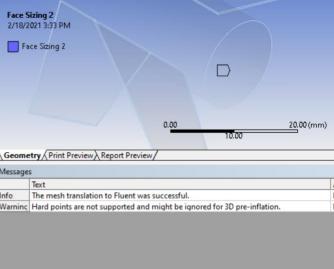
ņ Face Sizing 2/18/2021 3:33 PM Filter: Name -🕑 🔄 🐎 🕀 🙆 🛃 Face Sizing E Mesh ^ A Inflation Face Sizing 2 Edge Sizing 2 v Mamed Selections I. ņ Details of "Face Sizing" - Sizing 0.00 100.00 (mm) 50.00 Scope Scoping Method Geometry Selection Geometry Print Preview Report Preview Geometry 16 Faces Messages Definition Suppressed No Text As Element Size Info The mesh translation to Fluent was successful. Pr Туре Warninc Hard points are not supported and might be ignored for 3D pre-inflation. Pr Element Size 0.4 mm Advanced Defeature Size Default (0.2 mm) Size Function Uniform Behavior Soft Growth Rate Default (1.20)

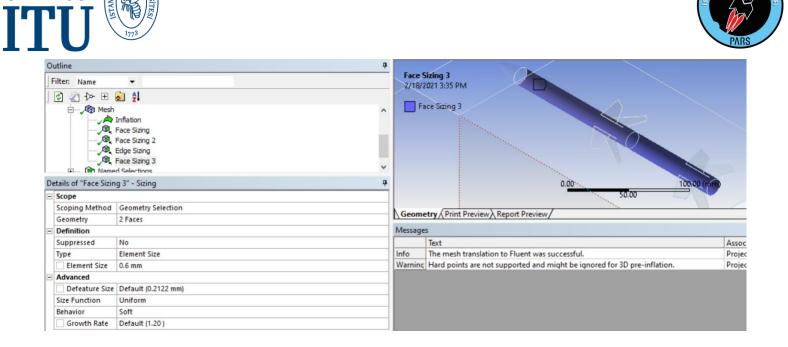
0	utline		7	
1	Filter: Name	×		Sizing 2 / 2021 3:33 PM
J	😰 🕢 🗠 🖽			
		Inflation Face Sizing Edge Sizing Face Sizing Face Sizing 3 d Selections	r F	ace Sizing 2
D	etails of "Face Sizin	g 2" - Sizing	4	0.00 20.00 (mm)
Ε	Scope			10.00
	Scoping Method	Geometry Selection	1000	etry (Print Preview) Report Preview/
	Geometry	1 Face	[\Geom	etry Print Preview A Report Preview/
Ε	Definition		Message	5
	Suppressed	No		Text
	Туре	Element Size	Info	The mesh translation to Fluent was successful.
	Element Size	0.4 mm	Warning	Hard points are not supported and might be ignored for 3D pre-inflation.
Ξ	Advanced			
	Defeature Size	Default (0.2 mm)		
	Size Function	Uniform		
	Behavior	Soft		
	Growth Rate	Default (1.20)		

Outline	4			/
Filter: Name	*	Edge 9	Sizing 021 3:34 PM	
🕼 🖉 🏷 🕀				
	Inflation Face Sizing Face Sizing 2 Edge Sizing 3 ed Selections	E	Ige Sizing	
Details of "Edge Sizi	ng" - Sizing 4		0.0 <u>00 10.000 (mm)</u>	1
- Scope			5.000	1
Scoping Method	Geometry Selection	Geom	try / Print Preview / Report Preview /	<u>II</u>
Geometry	64 Edges			
Definition		Message	5	
Suppressed	No		Text	Association
Туре	Element Size	Info	The mesh translation to Fluent was successful.	Project>Mod
Element Size	0.2 mm	Warning	Hard points are not supported and might be ignored for 3D pre-inflation.	Project>Mod
- Advanced				
Size Function	Uniform			
Behavior	Soft			
Growth Rate	Default (1.20)			
Bias Type	No Bias			









What we have obtained after all your sizing and which are the basic evaluation criteria for us; Our Aspect Ratio, Skewness and OQ values are given below:

Quality	
Check Mesh Qua	Yes, Errors
Target Skewn	0.6
Smoothing	Medium
Mesh Metric	Aspect Ratio
Min	1.1677
Max	735.67
Average	6.1101
Standard Devi	7.9879

Mesh Metric	Skewness 🔹
Min	1.9412e-004
Max	0.74883
Average	0.25318
Standard Deviation	0.15373

Mesh Metric	Orthogonal Quality 🔹
Min	4.8477e-002
Max	0.99836
Average	0.7434
Standard Deviation	0.15786

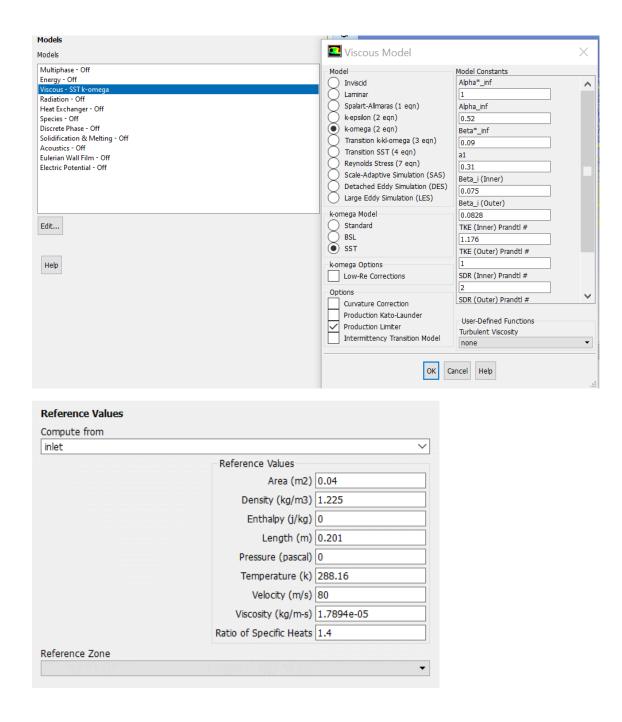




Our element count is as follows:

Statistics	
Nodes	1334446
Elements	4225210

-Setup







We could not add the Setup section to the report as a screenshot because we got an Ansys Workbench error at the end of our analysis. However, we were able to recover the images of our analysis results.

There are only minor differences with the reference rocket in the setup section:

- In the Reference Values section;

Area: 0.1 Velocity: 72.7324 Length: 0.253

- In the Boundary Conditions section;

Velocity Inlet, X-Velocity: 72.7324

Adjustments were made to be as follows, the remaining values remained the same as our reference rocket.

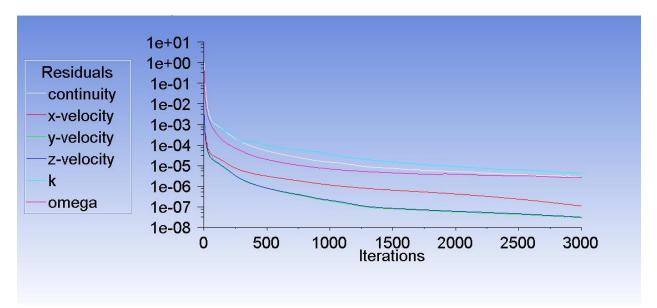
Solution Methods						
Pressure-Velocity Coupling						
Scheme		 	 	 		
Coupled						•
Spatial Discretization						
Gradient		 	 	 		^
Least Squares Cell Based					•	
Pressure		 	 			
Second Order					•	
Momentum		 	 	 		m
Second Order Upwind					•	
Turbulent Kinetic Energy		 	 	 		
Second Order Upwind					•	
Specific Dissipation Rate		 	 	 		
Second Order Upwind					•	\checkmark
Transient Formulation						
	V					
Non-Iterative Time Advancer	ment					
Frozen Flux Formulation						
Pseudo Transient						
✓ Warped-Face Gradient Correc	tion					
High Order Term Relaxation	Options					
Default						

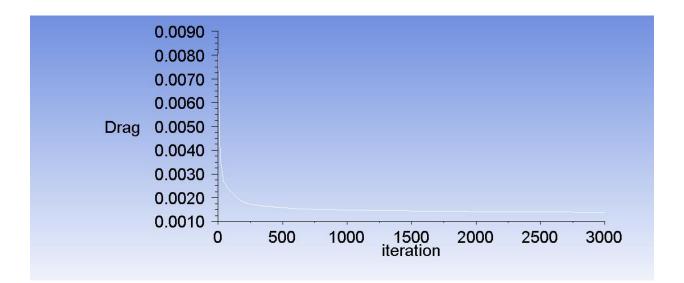




-Results

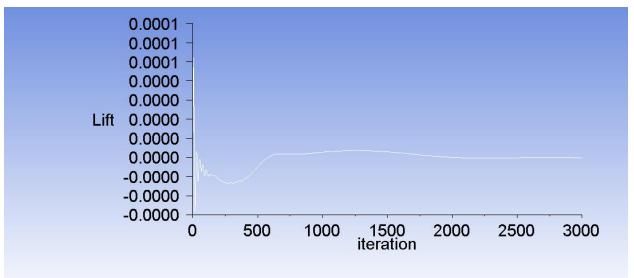
Before proceeding to the Results section, hybrid initialization was performed and the solution stage was started. Our solution graphics have been reached by giving approximately 3000 iterations. Drag and lift values were plotted simultaneously.



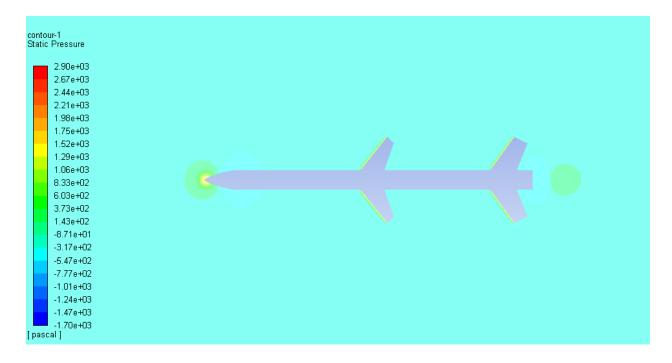








Pressure contours:

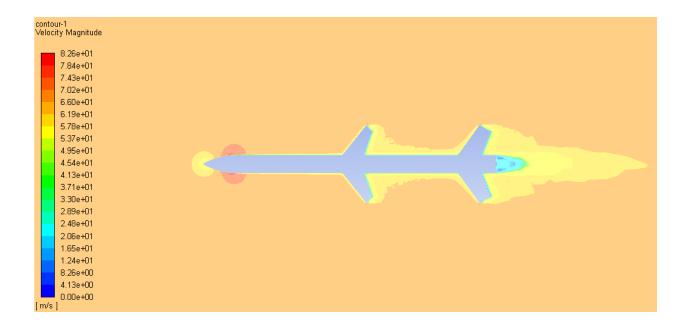


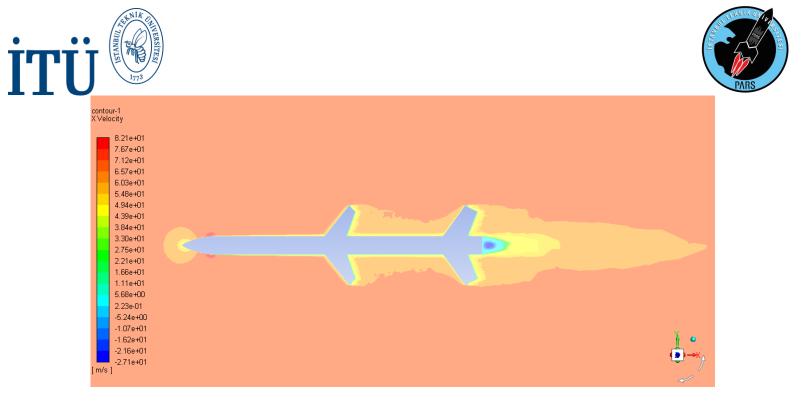




contour-1 Total Pressure 4.14e+03 3.85e+03	
3.57e+03 3.28e+03	
3.00e+03	
2.72e+03	
2.43e+03	
2.15e+03	
1.87e+03	
1.58e+03	
1.30e+03	
1.02e+03	
7.33e+02	
4.50e+02	
1.66e+02	
-1.17e+02	
-4.01e+02	
-6.85e+02	
-9.68e+02 -1.25e+03	
-1.25e+03 -1.54e+03	
[pascal]	

Velocity contours:



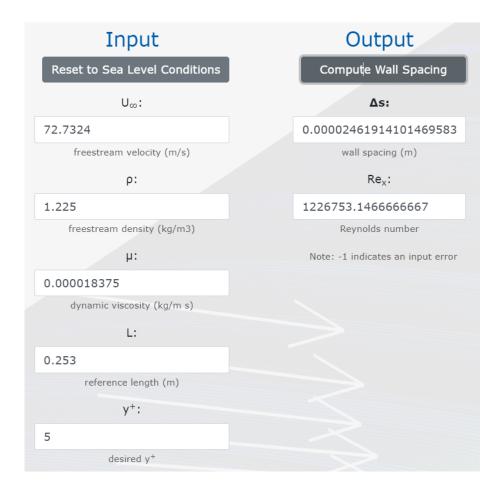


Thus, our Rocket 1-C analysis is completed.



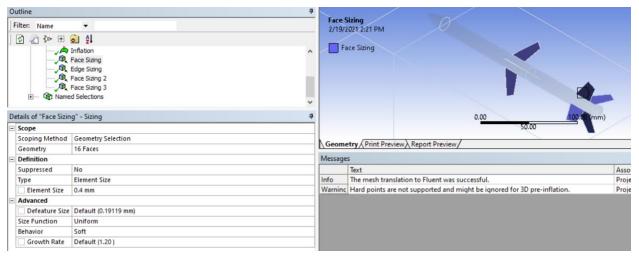


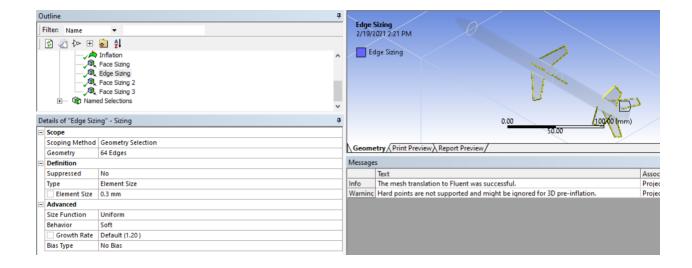
c) Multistage Rocket 1-C (Rotated 45 degrees) Ansys Analysis



-Mesh

D	Details of "Inflation" - Inflation 7	
Ξ	Scope	
	Scoping Method	Geometry Selection
	Geometry	2 Bodies
	Definition	
	Suppressed	No
	Boundary Scoping Method	Named Selections
	Boundary	wall
	Inflation Option	First Layer Thickness
	First Layer Height	2.4626e-002 mm
	Maximum Layers	10
	Growth Rate	1.2
	Inflation Algorithm	Pre





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		Inflation A Face Sizing Edge Sizing Face Sizing Tace Sizing 7 Face Sizing 3 d Selections V	Fa	cce Sizing 2	
(Details of "Face Sizin	g 2" - Sizing 7		0.00 40.00 (m	m)
8	Scope			20.00	
	Scoping Method	Geometry Selection	Garme	etry / Print Preview / Report Preview /	
	Geometry	1 Face	[/ Geome	ruy / Print Preview / Report Preview/	
E	Definition		Message	s	
	Suppressed	No	1	Text	Associa
	Туре	Element Size	Info	The mesh translation to Fluent was successful.	Project
	Element Size	0.4 mm	Warning	Hard points are not supported and might be ignored for 3D pre-inflation.	Project
E	Advanced				
	Defeature Size	Default (0.19119 mm)			
	Size Function	Uniform			
	Behavior	Soft			
	Growth Rate	Default (1.20)			









0	utline		ņ			
J	ilter: Name	•			iizing 3 021 2:22 PM	
]	😰 🖉 ি 🗄					
		Inflation Face Sizing Edge Sizing Face Sizing 2 Face Sizing 3 d Selections	^	Fa	cce Sizing 3	
D	tails of "Face Sizin	g 3" - Sizing	ą		0.000 <u>9.000</u> (m	im)
Ξ	Scope				4.500	
		Geometry Selection		Geome	etry (Print Preview) Report Preview/	
	,	24 Faces		-		
Ξ	Definition			Message		
	Suppressed	No			Text	Asso
	Туре	Element Size		Info	The mesh translation to Fluent was successful.	Proj
	Element Size	0.3 mm		Warning	Hard points are not supported and might be ignored for 3D pre-inflation.	Proj
Ξ	Advanced					
	Defeature Size	Default (0.15 mm)				
	Size Function	Uniform				
	Behavior	Soft				
	Growth Rate	Default (1.20)				

What we have obtained after all your sizing and which are the basic evaluation criteria for us; Our Aspect Ratio, Skewness and OQ values are given below:

Quality	
Check Mesh Qua	Yes, Errors
Target Skewn	0.6
Smoothing	Medium
Mesh Metric	Aspect Ratio
Min	1.1683
Max	665.2
Average	7.5994
Standard Devi	14.36

Mesh Metric	Skewness 🔹
Min	5.6867e-004
Max	0.79455
Average	0.27122
Standard Deviation	0.14701

Mesh Metric	Orthogonal Quality
Min 🗌	2.1451e-002
Max	0.9989
Average	0.72152
Standard Deviation	0.16166

Our element count is as follows:

Statistics	
Nodes	821610
Elements	2621531





Models Inviscid Alpha*_Inf Model Inviscid Imviscid Radiation - Off Spalart-Alimaras (1 eqn) Alpha*_Inf Species - Off Spalart-Alimaras (1 eqn) Alpha*_Inf Solidification & Melting - Off Kemega (2 eqn) Imviscid Acoustics - Off Transition Kkl-omega (3 eqn) Beta*_inf Solidification & Melting - Off Reynolds Stress (7 eqn) Scale-Adaptive Simulation (DES) Electric Potential - Off Scale-Adaptive Simulation (DES) Detached Eddy Simulation (DES) Edit Komega Model 0.075 Help komega Options I.176 KE (Unter) Prandtl # 1.176 SDR (Inner) Prandtl # SDR (Inner) Prandtl #
Energy - Off Inviscid Alpha*_inf Radiation - Off Spalart-Allmaras (1 eqn) Alpha_inf Species - Off Discrete Phase - Off 0.52 Solidification & Melting - Off k-omega (2 eqn) Beta*_inf Solidification & Melting - Off 0.09 a1 Eulerian Wall Film - Off Scale-Adaptive Simulation (SAS) Detached Eddy Simulation (LES) Detached Eddy Simulation (LES) Large Eddy Simulation (LES) Beta_i (Outer) Komega Model Standard BSL TKE (Inner) Prandtl # Help komega Options 1 SDR (Inner) Prandtl #
Options 2 Curvature Correction SDR (Outer) Prandtl # Production Kato-Launder User-Defined Functions Production Limiter Intermittency Transition Model OK Cancel

nlet		
	Reference Values	
	Area (m2)	0.1
	Density (kg/m3)	1.225
	Enthalpy (j/kg)	0
	Length (m)	0.253
	Pressure (pascal)	0
	Temperature (k)	288.16
	Velocity (m/s)	72.7324
	Viscosity (kg/m-s)	1.7894e-05
	Ratio of Specific Heats	1.4
eference Zone		



undary Conditions	3
ne Filter Text	÷
let	•
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mmetry all	⊕ ,
	1
Velocity Inlet	×
Zone Name inlet	
Momentum Thermal Radiation Species DPM Multipha	e Potential UDS
Velocity Specification Method Components	•
Reference Frame Absolute	•
Supersonic/Initial Gauge Pressure (pascal) 0 constant	-
Coordinate System Cartesian (X, Y, Z)	•
X-Velocity (m/s) 72.7324 constant	•
Y-Velocity (m/s) 0 constant	•
Z-Velocity (m/s) 0 constant	-
Turbulence	
Specification Method Intensity and Viscosity Ratio	-
Turbulent Intensity (%) 5	P
Turbulent Viscosity Ratio 10	Р
OK Cancel Help	

NL

ISTANBL

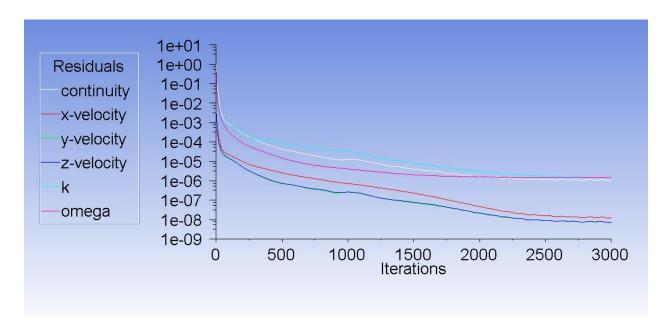
İTÜ

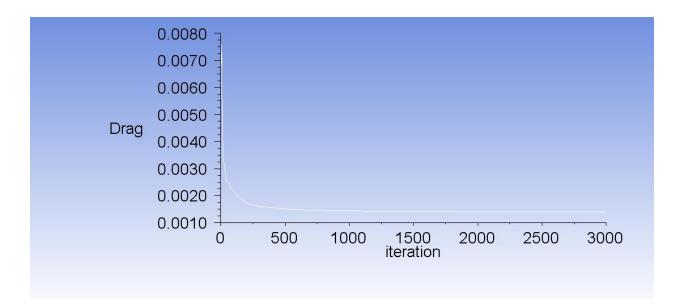
Solution Methods				
Pressure-Velocity Coupling				
Scheme				
Coupled				•
Spatial Discretization				
Gradient		 		~
Least Squares Cell Based			•	·
Pressure				
Second Order			•	•
Momentum		 		
Second Order Upwind			•	
Turbulent Kinetic Energy				71
Second Order Upwind				<u>.</u>
Specific Dissipation Rate				
Second Order Upwind				
Transient Formulation				
	∇			
Non-Iterative Time Advancer	nent			
Frozen Flux Formulation				
Pseudo Transient				
Warped-Face Gradient Correc	tion			
High Order Term Relaxation	Options			
Default				





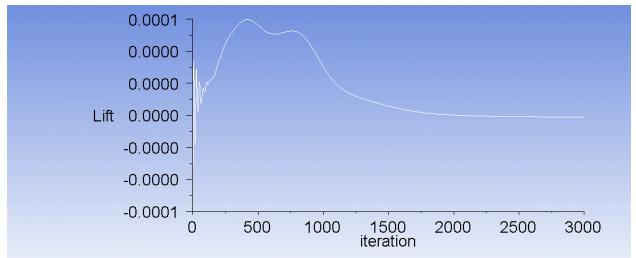
Before proceeding to the Results section, the solution phase was started by performing hybrid initiation. Our solution graphics were reached by giving approximately 3000 iterations. Drag and lift values were plotted simultaneously.



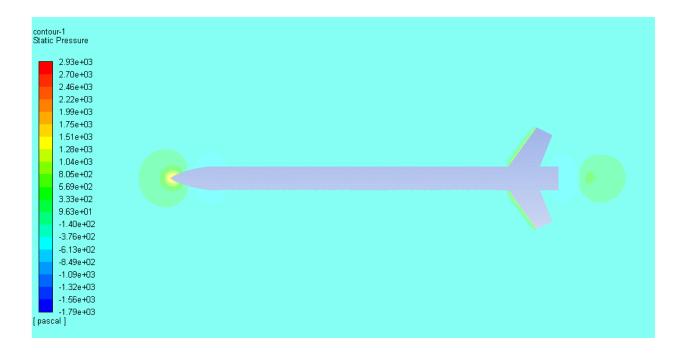


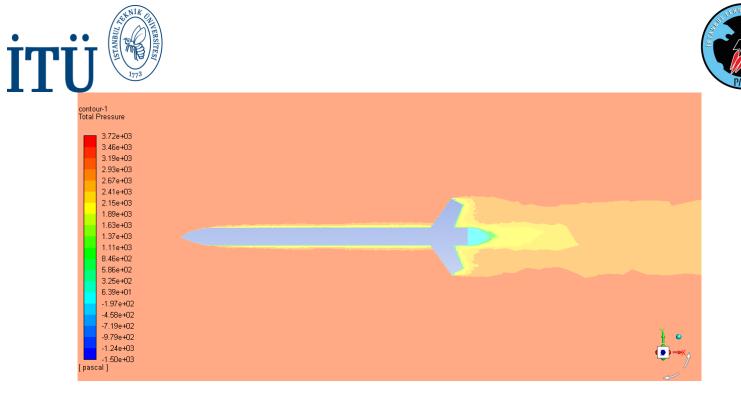




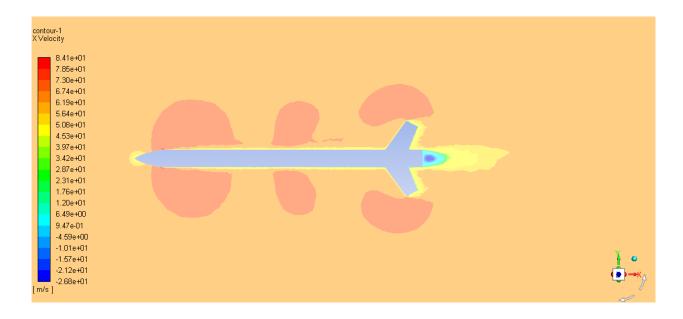


Pressure contours:



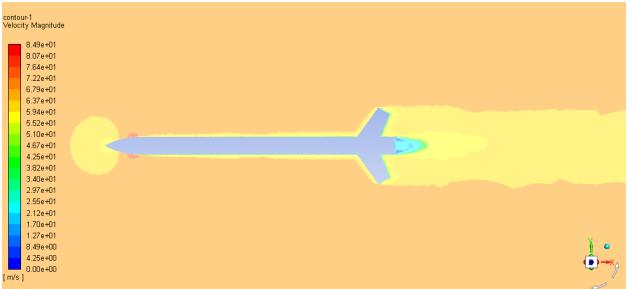


Velocity contours:







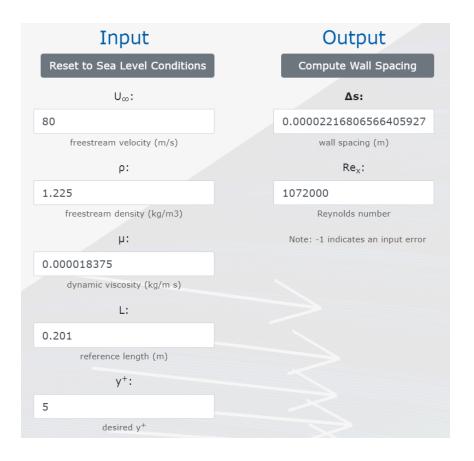


Rocket 1-C (Rotated 45 Degrees) analysis is complete.





d) Reference Rocket (Inverted Fins) Ansys Analysis

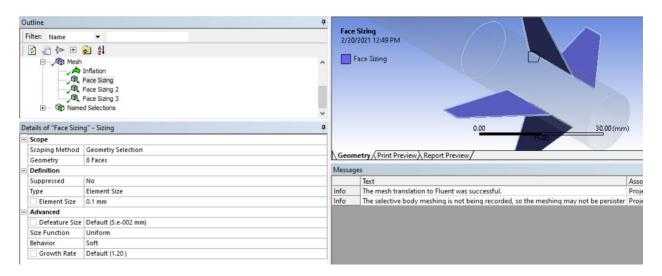


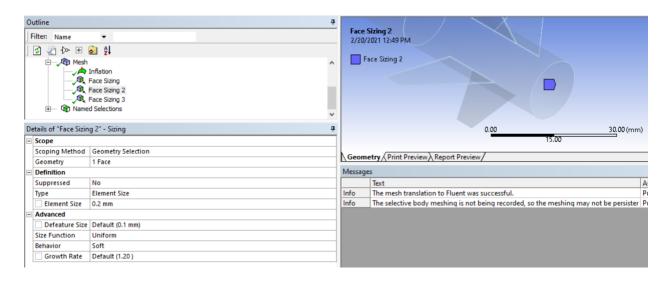
- Mesh

De	tails of "Inflation" - Inflation		
Ξ	Scope	cope	
	Scoping Method	Geometry Selection	
	Geometry 2 Bodies		
Ξ	Definition		
	Suppressed	No	
	Boundary Scoping Method	Named Selections	
	Boundary	wall	
	Inflation Option	First Layer Thickness	
	First Layer Height	2.216e-002 mm	
	Maximum Layers	10	
	Growth Rate	1.2	
	Inflation Algorithm Pre		









			₽	-	2/20/2	Sizing 3 LO21 12:50 PM ace Sizing 3	
D	etails of "Face Sizin	d Selections a 3" - Sizina	~ 4			0.000 10.000 (1	nmì
	Scope	y		1		5.000	
		Geometry Selection		I.			
	Geometry	4 Faces		Ľ	Geome	etry / Print Preview / Report Preview /	
Ξ	Definition	·		1	Message	5	
	Suppressed	No		1		Text	Asso
	Туре	Element Size			Info	The mesh translation to Fluent was successful.	Proje
	Element Size	0.2 mm			Info	The selective body meshing is not being recorded, so the meshing may not be persister	Proje
Ξ	Advanced						
	Defeature Size	Default (0.1 mm)					
	Size Function	Uniform					
	Behavior	Soft					
	Growth Rate	Default (1.20)					





What we have obtained after all your sizing and which are the basic evaluation criteria for us; Our Aspect Ratio, Skewness and OQ values are given below:

Quality	
Check Mesh Qua	Yes, Errors
Target Skewn	0.6
Smoothing	Medium
Mesh Metric	Aspect Ratio
Min	1.1608
Max	955.84
Average	3.5682
Standard Devi	7.315

Mesh Metric	Skewness 🔹
Min	1.6528e-005
Max	0.94277
Average	0.25003
Standard Deviation	0.14373

Mesh Metric	Orthogonal Quality
Min	1.2538e-002
Max	0.9994
Average	0.74938
Standard Deviation	0.14379

Our element count is as follows:

Statistics	
Nodes	1685019
Elements	4343587





Models			
Models	💶 Viscous Model		\times
Multiphase - Off Energy - Off Viscous - SST k*omega Radiation - Off Heat Exchanger - Off Species - Off Discrete Phase - Off Solidification & Melting - Off Acoustics - Off Eulerian Wall Film - Off Electric Potential - Off Help	Model Inviscid Laminar Spalart-Allmaras (1 eqn) k-epsilon (2 eqn) k-omega (2 eqn) Transition skl-omega (3 eqn) Transition SST (4 eqn) Reynolds Stress (7 eqn) Scale-Adaptive Simulation (SAS) Detached Eddy Simulation (DES) Large Eddy Simulation (LES) komega Model Standard BSL • SST komega Options Low-Re Corrections Options Curvature Correction Production Kato-Launder Production Imiter	Model Constants Alpha*_inf 1 Alpha_inf 0.52 Beta*_inf 0.09 a1 0.31 Beta_i (Inner) 0.075 Beta_i (Outer) 0.0828 TKE (Inner) Prandtl # 1.176 TKE (Outer) Prandtl # 1 SDR (Inner) Prandtl # 2 SDR (Outer) Prandtl # User-Defined Functions Turbulent Viscosty	~
	Intermittency Transition Model	none ancel Help	•

Reference Values		
Compute from		
inlet		~
	Reference Values	
	Area (m2)	0.04
	Density (kg/m3)	1.225
	Enthalpy (j/kg)	0
	Length (m)	0.201
	Pressure (pascal)	0
	Temperature (k)	288.16
	Velocity (m/s)	80
	Viscosity (kg/m-s)	1.7894e-05
	Ratio of Specific Heats	1.4
Reference Zone		

				S
Boundary Conditions				
Zone Filter Text			-0 -	÷
inlet				€.
interior-part-solid outlet				
symmetry wall				⊕ 、
				,
Velocity	(Inlet			
	miller			
Zone Name inlet				
Momentum	Thermal Radiation	Species DF	M Multiphas	e Poi
	Thermal Radiation	Species DF	Multiphas	e Pot
	ty Specification Method Comp	onents	Multiphas	e Pot
Veloci	ty Specification Method Comp Reference Frame Absol	onents		e Pot
Veloci	ty Specification Method Comp Reference Frame Absolu I Gauge Pressure (pascal) 0	onents ute	Multiphas	e Pot
Veloci	ty Specification Method Comp Reference Frame Absol	onents ute		e Poi
Veloci	ty Specification Method Comp Reference Frame Absoli I Gauge Pressure (pascal) 0 Coordinate System Cartes	onents ute	constant	e Pol
Veloci	ty Specification Method Comp Reference Frame Absoli I Gauge Pressure (pascal) 0 Coordinate System Cartes X-Velocity (m/s) 80	onents ute	constant	e Pot
Veloci Supersonic/Initia	ty Specification Method Comp Reference Frame Absolu I Gauge Pressure (pascal) 0 Coordinate System Cartes X-Velocity (m/s) 80 Y-Velocity (m/s) 0 Z-Velocity (m/s) 0 Turbulence	onents ute sian (X, Y, Z)	constant constant constant constant	e Pot
Veloci Supersonic/Initia Phase	ty Specification Method Comp Reference Frame Absolution I Gauge Pressure (pascal) (0) Coordinate System Cartes X-Velocity (m/s) (80) Y-Velocity (m/s) (0) Z-Velocity (m/s) (0) Turbulence Specification Method Intensi	onents ute sian (X, Y, Z) Ity and Viscosity Rati	constant constant constant constant	e Por
Veloci	ty Specification Method Comp Reference Frame Absolu I Gauge Pressure (pascal) 0 Coordinate System Cartes X-Velocity (m/s) 80 Y-Velocity (m/s) 0 Z-Velocity (m/s) 0 Turbulence Specification Method Intensi	onents ute sian (X, Y, Z)	constant constant constant constant	e Poi

Solution Methods

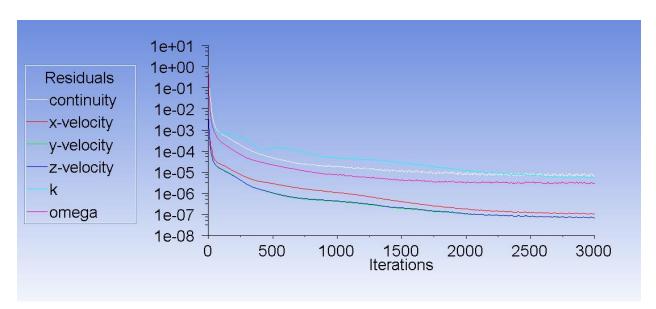
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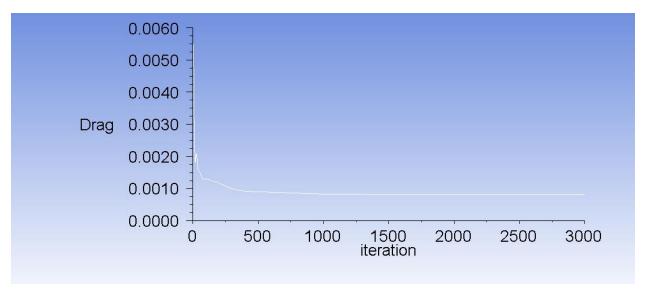






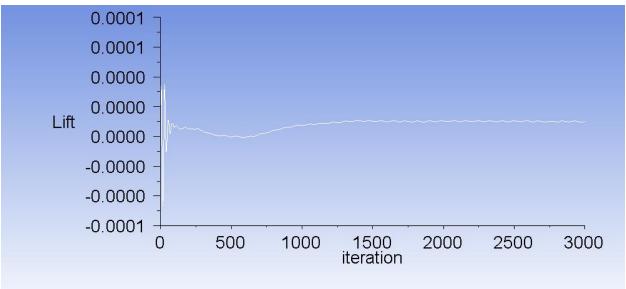
Before proceeding to the Results section, the solution phase was started by performing hybrid initiation. Our solution graphics were reached by giving approximately 3000 iterations. Drag and lift values were plotted simultaneously.



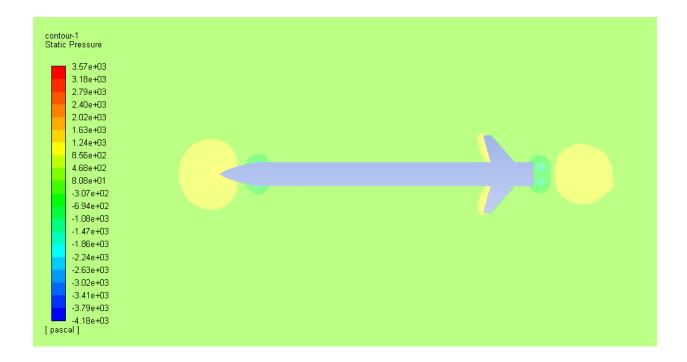






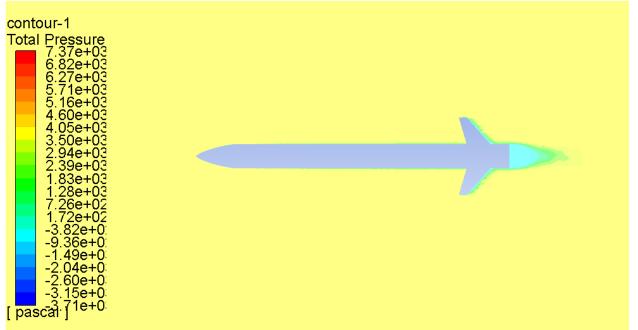


Pressure contours:

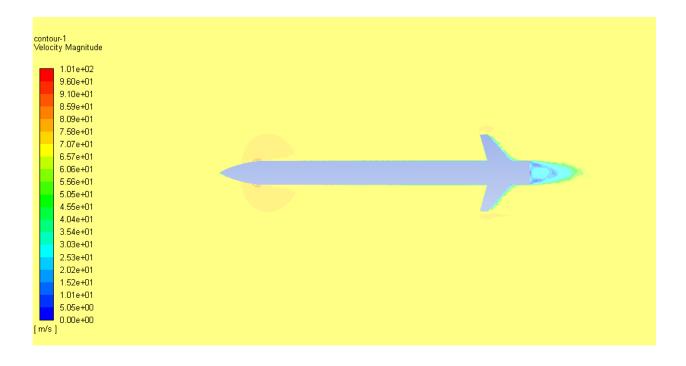








Velocity contours:







9.97e+01	
9.33e+01	
8.69e+01	
8.05e+01	
7.40e+01	
6.76e+01	
6.12e+01	
5.48e+01	
4.83e+01	
4.19e+01	
3.55e+01 2.91e+01	
2.26e+01 1.62e+01	
9.80e+00	
3.37e+00 -3.05e+00	
-3.05e+00 -9.48e+00	
-9.48e+00 -1.59e+01	
-1.59e+01 -2.23e+01	
-2.238401	

And with the end of this analysis, all our ANSYS analyzes have been completed.





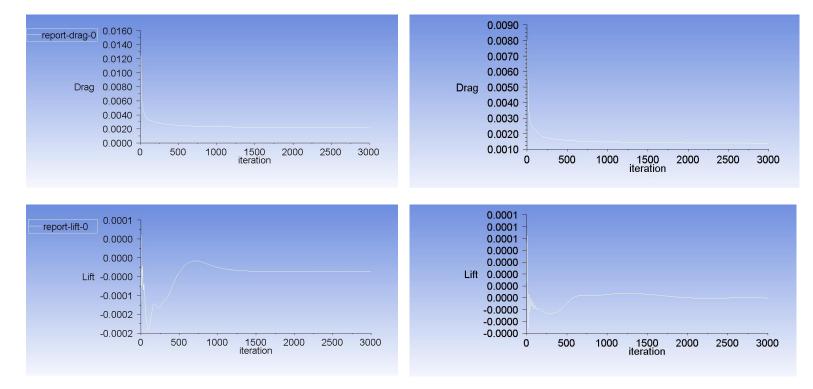
5)Interpretation of Results and Analysis

First of all, it has been deemed appropriate by us to touch on how the interpretation is made.

-Drag And Lift

Since the fluctuations of the lift and drag graphs are related to the mesh, the values in which the drag and lift values become stable in these graphs are the basic value that is important for us. In our ANSYS analysis; Since our rocket fins were designed to be rectangular and inserted perpendicular to the flow in the analysis, we expected the drag and lift values of all our rockets to be 0, and the analysis results came in accordance with these expectations.

All of our drag and lift values are below so that you can compare and see them more easily. given in order:

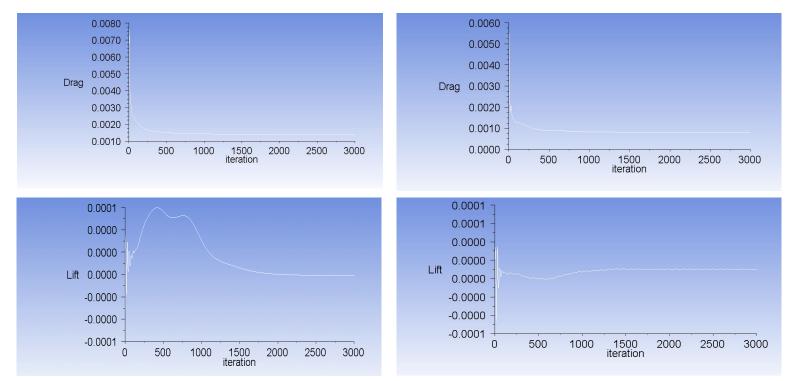


(Reference Rocket)

(Rocket 1-C)







(Rocket 1-C (Rotated 45 Degrees)

(Reference Rocket (With Inverted Fins)))





-Pressure and Velocity Contours

While examining the pressure and velocity contours, we need to look at two critical points as the aerodynamics section, and the first critical point is the nose cone. Looking at the analysis results, you can see that all rockets have certain shock bursts in their nose cones. However, the magnitudes of these shocks gave different results in each analysis. The fact that these shocks are large will mean that the material of the nose cone is made of materials that are more resistant to the pressure and temperature that will occur, which is reflected as additional material damage to our rocket, and therefore designs that are subject to large shocks should be avoided as much as possible.

When we look carefully, we can easily say that our reference rocket was less shocked than other rockets, and 1-C rockets were also exposed to a shocking shock. However, as a result of the analysis of the reverse finned reference rocket, the amount of shock in the nose cones is larger than the other rockets. Therefore, this design should not be preferred.

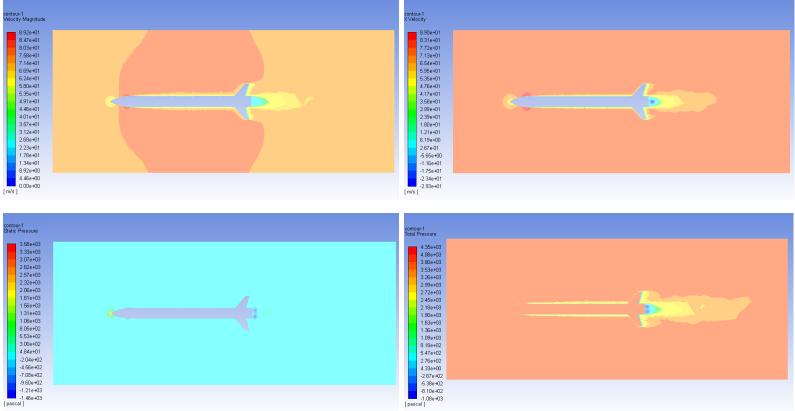
Our second critical point is the fins. The part we will compare is the static pressure contour part. As a rocket team, we want the static pressure value to be at a minimum on the fin. Because the magnitude of this pressure value is due to the pressure applied to the fin.

It shows whether the rocket can exhibit a stable flight. Considering this information, when we examine our rocket analysis, it is not difficult to say that our reference rocket gives the best results. Similarly, 1-C rockets showed acceptable results, while our reverse finned reference rocket showed a very poor result.

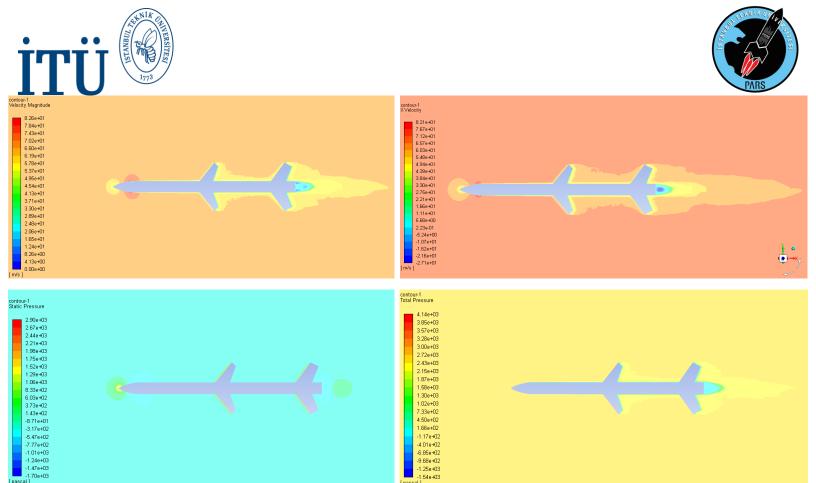
Below, we have given these contours in order to be able to compare them more easily:





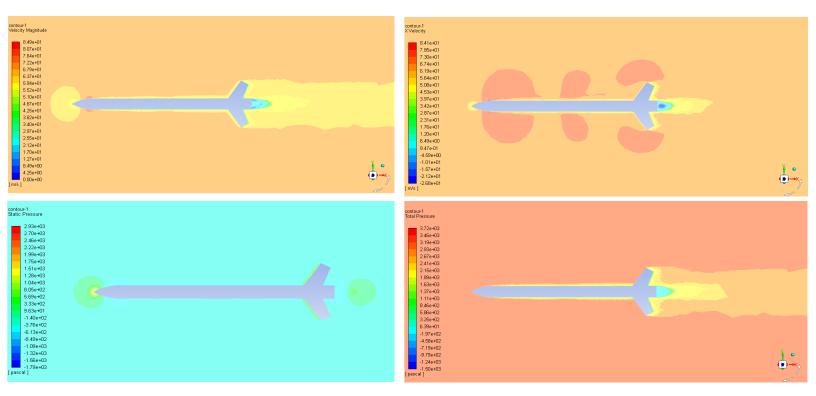


(Reference Rocket)

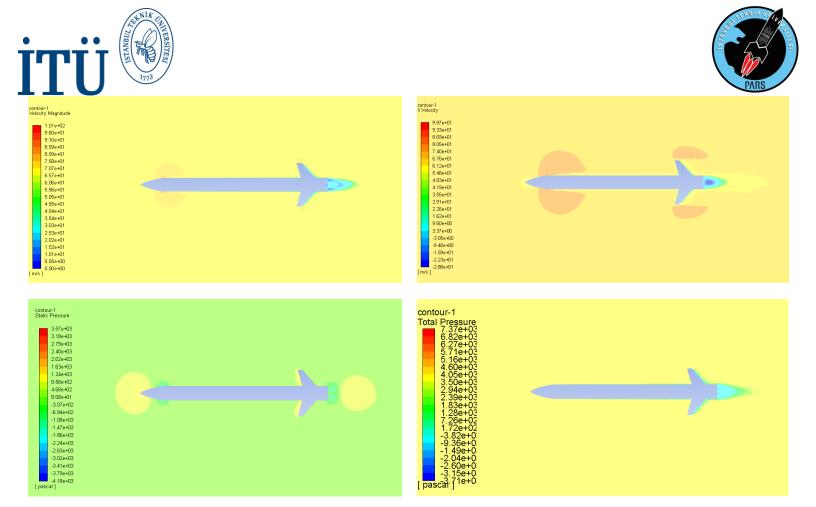


(Rocket 1-C)

pascal



(Rocket 1-C (Rotated 45 Degrees))



(Reference Rocket (Inverted Wing))

As a result, when we look at; Our reference rocket is a successful rocket. Our inverted finned reference rocket has been a clear example of the worst rocket types that can be designed, and our main intention in designing and analyzing this rocket was to prove, with concrete evidence, why this rocket should not be preferred. When we look at our Multistage 1-C rockets, we see rockets that can be built and fly as we expected from our Openrocket analysis. However, since the shock values on these rockets are higher than our reference rocket, they must be made of materials that are more resistant to these shocks and have relatively high heat resistance. This will be reflected to us as an additional cost. In addition, although we could not present it to you in these analyzes, in a multistage rocket that performs an angled flight, the front fins will inevitably reduce the lift on the rear winglets, which will cause various optional changes such as playing with the size of the rear winglets. So our rocket will become a bigger and more costly rocket.

As PARS Rocket Group, we are not planning a multistage rocket study for now, but our results of these multistage rocket analysis can be reused and further detailed by the group if necessary.

And as a result of all these design, analysis and examinations, it is sufficient to make the following summary:





Attachment of additional fins to a rocket; It is an unnecessary action unless there are additional tasks such as a multistage rocket flight or steering the rocket. Because the additional fins to be installed require us to enlarge the rocket and make it from materials that are more resistant to new shocks that may occur. And a bigger, more durable rocket means we have to spend more. Apart from these high costs, the increasing rocket weight will cause us to experience additional altitude loss, and balancing this loss requires the design of a multi-engine multistage rocket.

Considering these conditions, it would be an unnecessary action for us to attach an additional fin to our rockets that we will plan as PARS Rocket Group.

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